



JACOBS  
UNIVERSITY



Study Program Handbook

## Intelligent Mobile Systems

Bachelor of Science

## Subject-specific Examination Regulations for Intelligent Mobile Systems (Fachspezifische Prüfungsordnung)

The subject-specific examination regulations for Intelligent Mobile Systems are defined by this program handbook and are valid only in combination with the General Examination Regulations for Undergraduate degree programs (General Examination Regulations = Rahmenprüfungsordnung). This handbook also contains the program-specific Mandatory Module and Examination Plans (Appendix 1a / 1b).

Upon graduation, students in this program will receive a Bachelor of Science (BSc) degree with a scope of 180 ECTS (for specifics see chapter 3 of this handbook).

Version	Valid as of	Decision	Details
Fall 2016 - V1	01.09.16	AB August 2016	Master Version
Fall 2016 - V2	01.09.17	Dean W. Nau 11/16 + 03/17 / AB August 2017	Minor curricula changes see appendix 1a/1b / 2.2 revised, 2.5 added
Fall 2016 - V3	01.09.18	Academic Senate August 29, 2018	Figure 3 updated

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# 1 The Intelligent Mobile Systems Study Program

## 1.1 Concept

This program covers engineering methods and technologies that are relevant for freeing artificial mobile systems from permanent human supervision, i.e., that enable mobile systems to perform autonomous intelligent operations. Application areas include the automotive and transport industries, robotics and automation, communication technologies, marine technology, and logistics. The program also includes transdisciplinary aspects related to the study of processes that enable mobility in intelligent natural systems. Hands-on experiences with technical systems and methods are provided in first-class labs.

## 1.2 Specific Advantages of the IMS Program at Jacobs University

- IMS is the flagship program of the university in the focus area Mobility. It has been designed to be very interdisciplinary incorporating concepts from various engineering disciplines such as Computer Science, Electrical Engineering, Mechanical Engineering, and Logistics.
- While programs on Automation, Robotics, and Mechatronics exist in other universities, what makes IMS stand out is that, in addition to covering the aforementioned areas, it puts a special emphasis on the key concepts of Intelligence and Autonomy which are important for the man-made systems of the future. Hence, students are given a solid background in fields such as Control Systems, Machine Learning, Computer Vision, Planning, and Optimization.
- The IMS program is geared towards the world-renowned automation and robotics industry in Germany. As confirmed by keyword-searches on popular job-portals, engineers with additional skills in Vision, Machine Learning, and Robotics are much sought after by the well-established German and European automobile industry. An extended internship in the fifth semester allows students to gain industrial experience and make contacts for potential future job opportunities.
- Many IMS faculty members have research-groups that are well-funded by EU and DFG projects. Hence, ample opportunities exist for students to get involved and gain research experience.

## 1.3 Program-Specific Qualification Aims

### Knowledge and Understanding

After finishing this program, the student will have knowledge and understanding of

- Kinematics and dynamics of multi-body systems
- Linear and nonlinear control systems
- Basic electronics, operational principles of motors and drives

- Machine Learning algorithms and techniques for pattern-recognition, classification, and decision-making under uncertainty
- Computer Vision algorithms for inferring 3D information from camera images, and for object recognition and localization
- Robotic manipulators and mobile robots
- Simultaneous Localization and Mapping (SLAM) algorithms
- Motion planning techniques in robotics
- Relevant sensors, signal-processing, and probabilistic estimation techniques
- Analytical and numerical optimization in continuous and discrete domains

### **Ability**

After finishing this program, the student will be capable of designing and implementing complete intelligent mobile systems that carry out complex tasks in challenging environments without permanent human supervision. Concretely, the student will be able to

- Model common mechanical and electrical systems which are part of intelligent mobile systems
- Design control systems and tune their performance
- Design and program image-processing and computer-vision algorithms
- Select and implement classification and pattern recognition algorithms for real-world problems
- Design robots and program them using popular robotics software frameworks
- Formulate and solve optimization problems of both theoretical and practical natures, in continuous as well as discrete settings
- Work in a team to develop and integrate different components into a functioning system

## **1.4 The Jacobs University Employability and Personal Development Concept**

Jacobs University's educational concept aims at fostering employability which refers to skills, capacities, and competencies which transcend disciplinary knowledge and allow graduates to quickly adapt to professional contexts. Jacobs University defines employability as encompassing not just technical skills and understanding but also personal attributes and qualities enabling students to become responsible members of their professional and academic fields as well as of the societies they live in.

Graduates of JU will be equipped with the ability to find employment and to pursue a successful professional career, which means that

- graduates possess the ability to acquire knowledge rapidly, to assess information and to evaluate new concepts critically;
- graduates have communicative competences which allow them to present themselves and their ideas and to negotiate successfully;

- graduates are familiar with business-related processes and management skills and are able to manage projects efficiently and independently.

Graduates of JU will also be equipped with a foundation to become globally responsible citizens, which includes the following attributes and qualities:

- graduates have gained intercultural competence; they are aware of intercultural differences and possess skills to deal with intercultural challenges; they are familiar with the concept of tolerance;
- graduates can apply problem-solving skills in negotiating and mediating between different points of view;
- graduates can rely on basic civic knowledge and have an understanding for ethical reasoning; students are familiar with the requirements for taking on responsibility.

## 1.5 Career Options

Careers in research and development or management tracks in automotive and transport, robotics and automation, communication technologies, marine technology and logistics industries. Given the increasing need for automation of daily life tasks through intelligent mobile systems, there is a significant number of career options in addition to the core ones that are covered in the program.

## 1.6 More Information and Contact

For more information please contact the study program coordinator:

Dr. Francesco Maurelli

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Telephone: +49 421 200-3103

or visit our program website: <http://imsys.user.jacobs-university.de/>

## 2 The Curricular Structure

### 2.1 General

The undergraduate education at Jacobs University equips students with the key qualifications necessary for a successful academic, as well as professional career. By combining disciplinary depth and transdisciplinary breadth, supplemented by skills education and extracurricular elements, students are prepared to be responsible and successful citizens within the societies they work and live in.

The curricular structure provides multiple elements enhancing employability, transdisciplinarity, and internationality. The unique Jacobs Track, offered across all study programs, provides a broad range of tailor-made courses designed to foster career competencies. These include courses which promote communication, technology, business, (German) language, and management skills. The World Track, included in the third year of study, provides extended company internships or study abroad options. Thus students gain training on the job and intercultural experiences. All undergraduate programs at Jacobs University are based on a coherently modularized structure, which provides students with a broad and flexible choice of study plans to meet their major as well as minor study interests.

The policies and procedures regulating undergraduate study programs at Jacobs University in general can be found on the website.

### 2.2 The Jacobs University 3C-Model

Jacobs University offers study programs according to the regulations of the European Higher Education Area. All study programs are structured along the European Credit Transfer System (ECTS), which facilitates credit transfer between academic institutions. The three-year undergraduate program involves six semesters of study with a total of 180 ECTS credits. The curricular structure follows an innovative and student-centered modularization scheme - the 3C-Model - which groups the disciplinary content of the three study years according to overarching themes:

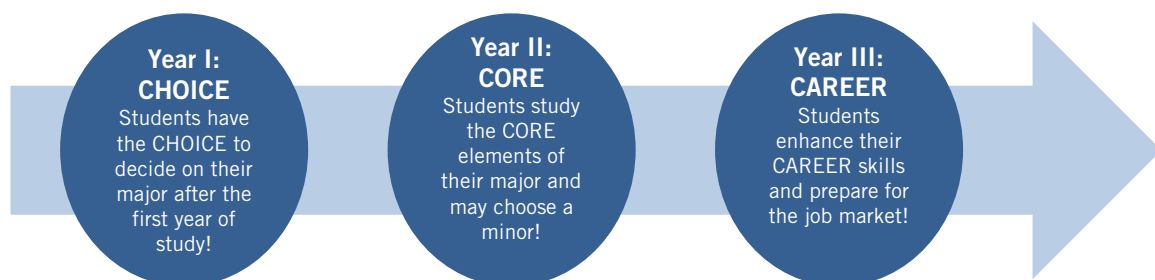


Figure 1: The Jacobs University 3C-Model

### 2.2.1 YEAR 1 - CHOICE

The first study year is characterized by a broad offer in disciplinary and interdisciplinary education. Students select three CHOICE modules from a variety of study programs. As a unique asset, our curricula allow students to select their study program freely from among the three selected CHOICE modules during their first year of study.

### 2.2.2 YEAR 2 - CORE

In the second year, students take three in-depth, discipline-specific CORE modules. One CORE module can also be taken from a second, complementary discipline, which allows students to incorporate a minor study track into their undergraduate education. Students will generally qualify for a minor if they have successfully taken at least one CHOICE module and one CORE module in a second field, and this extra qualification will be highlighted in the transcript.

### 2.2.3 YEAR 3 - CAREER

During their third year, students must decide on their career after graduation. In order to facilitate this decision, the fifth semester introduces two separate tracks. By default students are registered for the World Track.

#### 1. The World Track

In this track there are two mandatory elective options:

- **Internship**

The internship program is a core element of Jacobs University's employability approach. It includes a mandatory semester-long internship off-campus (minimum 16 weeks in full-time) which provides insight into the labor market as well as practical work experience related to the respective area of study. Successful internships may initiate career opportunities for students. For more information, please contact the Career Services Center (<http://www.jacobs-university.de/career-services/contact>).

- **Study Abroad**

Students can take the opportunity to study abroad at one of our partner universities. Courses recognized as study abroad credits need to be pre-approved according to the Jacobs University study abroad procedures and carry minimum of 20 ECTS credits in total. Several exchange programs allow you to be directly enrolled at prestigious partner institutions worldwide. Jacobs University's participation in Erasmus+, the European Union's exchange program, provides an exchange semester at a number of European universities including Erasmus study abroad funding.

For more information, please contact the International Office (<http://intoffice.user.jacobs-university.de/outgoing/>).

#### 2. The Campus Track

Alternatively, students may also opt to follow the Campus Track by continuing their undergraduate education at Jacobs, namely by selecting an additional CORE module during their third year and redistributing the remaining courses and modules across the third year. This opportunity can be used by students to more intensively focus on their major or to fulfill the minor requirements for a second field of interest.



In the sixth semester, all students select from a range of specialization courses within their study program and concentrate on their Bachelor thesis in the context of a Project/Thesis Module.

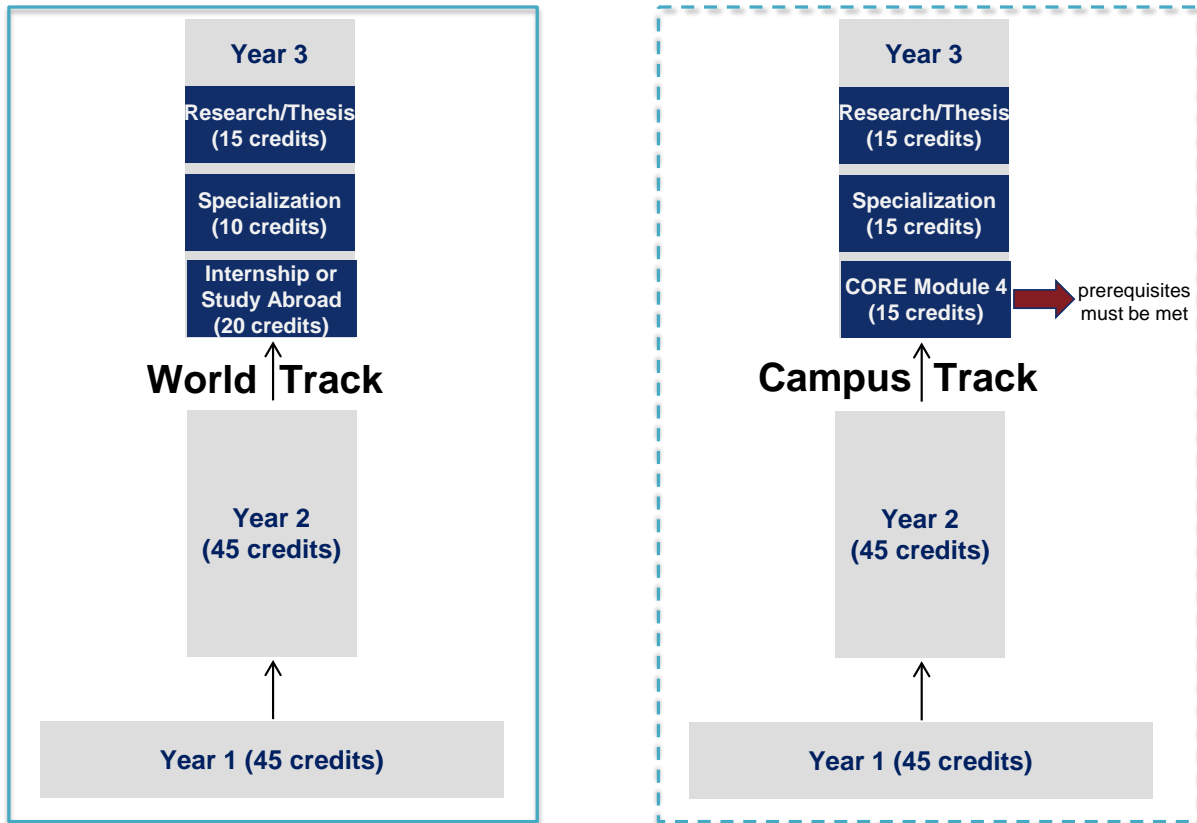


Figure 2: World Track versus Campus Track

## Career Skills

Throughout their studies all students attend a mandatory set of career skills courses and events.

The mandatory Career Skills module prepares all undergraduate students at Jacobs University for the transition from student life to working life as well as for their future career. Skills, knowledge and information which are fundamental for participation in an internship or a semester abroad will be conveyed concurrently. Essential components of the module include information sessions, compulsory seminars on various career-relevant topics as well as participation in the annual Jacobs Career Fair.

The successful completion of the Career Skills Module and the encompassed single seminars are graded with Pass/Fail for all students. ECTS credits are not awarded. All undergraduate students will be automatically registered for the Career Skills Module. However, every student has to keep track of his/her individual fulfillment of requirements and has to register on Campusnet for all seminars and sessions during the official registration period at the beginning of each semester. An overview of the sequence in which components should be completed is shown in the table below:

**CAREER SKILLS MODULE** For Undergraduate Students matriculated Fall 2015 and Fall 2016

SEMESTER	1	2	3	4	5	6
MANDATORY BASICS	CSC-INFO Session: "CSC Services" CA01-990000		CSC-INFO Session: "World Track" CA01-990026			
MANDATORY SEMINARS	Both seminars have to be attended in your first or second semester.  CSC-APPLICATION TRAINING CA01-990001  CSC-RESEARCHING & CONTACTING EMPLOYERS CA01-990004					
MANDATORY ELECTIVE SEMINARS (seminar program subject to availability)			Attend 2 out of several career skills seminars and workshops. i.e.  <ul style="list-style-type: none"> <li>▪ Business Etiquette ▪ Presentation Skills</li> <li>▪ Communication Skills ▪ Grad School Application Training</li> <li>▪ Self-Management ▪ Time-Management</li> <li>▪ Decision Making ▪ Preparing for an Interview</li> <li>▪ Introduction to Project Management</li> </ul>			
OTHER MANDATORY COMPONENTS				CSC-JACOBS CAREER FAIR in February, on campus CA01-990003	INTERNSHIP or STUDY ABROAD or CAMPUS TRACK	INTERNSHIP & STUDY ABROAD EVENT  Online CSC-CAREER SURVEY CA01-990002

Figure 3: The Career Skills Module

## 2.3 The Jacobs Track

The Jacobs Track, another stand-alone feature of Jacobs University, runs parallel to the disciplinary CHOICE, CORE, and CAREER modules across all study years and is an integral part of all study programs. It reflects our commitment to an in-depth methodological education, it fosters our transdisciplinary approach, it enhances employability, and equips students with extra skills desirable in your general field of study. Additionally, it integrates essential language courses.

Mathematics, statistics, and other methods courses are offered to all students within a comprehensive Methods Module. This module provides students with general foundations and transferable techniques which are invaluable to follow the study content not only in the study program itself but also in related fields.

The Skills Module equips students with general academic skills which are indispensable for their chosen area of study. These could be, for example, programming, data handling, presentation skills, and academic writing, scientific and experimental skills.

The transdisciplinary Triangle Module offers courses with a focus on at least one of the areas of business, technology and innovation, and societal context. The offerings comprise essential knowledge of these fields for students from other majors as well as problem-based courses that tackle global challenges from different disciplinary backgrounds. Working together with students from different disciplines and cultural backgrounds in these courses broadens the students horizon by crossing the boundaries of traditional disciplines.

Foreign languages are integrated within the Language Module. Communicative skills and foreign language competence foster students intercultural awareness and enhance their employability in a globalized and interconnected world. Jacobs University supports its students in acquiring and improving these skills by offering a variety of language courses at all proficiency levels. Emphasis is put on fostering German language skills, as they are an important prerequisite for students to learn about, explore, and eventually integrate into their host country. Hence, acquiring 10 ECTS credits in German is a requirement for all students. Students who meet the requirements of the German proficiency level (e.g. native speakers) are required to select courses in any other language program offered.

## 2.4 Modularization of the Intelligent Mobile Systems Program

### 2.4.1 Content

#### Year 1

Take the mandatory module listed below and select two further CHOICE modules from a different study area.

#### **Introduction to Intelligent Mobile Systems (CH09-IntroIMS)**

This is an introductory module providing a strong theoretical and practical foundation for the core courses in the second year. The key components required to make man-made mobile systems intelligent are sensors, actuators, and algorithms. Students will be given an overview of

basic technologies and concepts underlying each of these components. The module will cover the fundamental engineering tools to model mechanical, electrical, and mechatronic systems. A detailed introduction to linear systems theory will be provided, aided by computer simulation. Finally, you will get an introduction to basic electronics and complement your knowledge with lab exercises.

## Year 2

Take all three modules or replace one with a CORE module from a different study program.

### Intelligent Systems (CO22-IntelSys)

This module teaches you about core technologies and algorithms which endow a man-made system with intelligence. You will learn how machines can process sensor data, including visual data, to perceive and represent their surroundings. Once an environment representation is available, an intelligent machine, such as a robot, can act on and change its environment after deliberate planning. Utilizing its accumulated experience, the machine can learn and adapt its behavior in the future. This module covers all of these aspects and thus gives you an in-depth understanding of machine perception and learning, as well as robotics.

### Automation and Control (CO23-AutoControl)

This module builds on top of the material learnt in the "Introduction to IMS" module and covers the general areas of control and automation, including also an introductory course in electronics with an accompanying lab. Topics covered include (but are not limited to): stability analysis, frequency (Laplace) domain modeling of systems, Bode plots, programmable controllers, basic electronics, and sensors and actuators used in industrial automation.

### Planning and Optimization (CO24-PlanOpt)

This module is focused on developing the mathematical and engineering skills required to plan for and optimize complex systems such as Intelligent Mobile Systems. It contains two courses on optimization: one focusing on quantitative methods and techniques for effective decision making, and the other dedicated to broader optimization problems, covering topics such as Lagrange multipliers, convex, and nonlinear programming. A third course focuses on planning and decision-making algorithms for autonomous systems.

Some CORE Modules require students to have taken a specific CHOICE Module. Please see the Module Handbook for details regarding pre-requisites.

## Year 3

In the 3rd year students follow the World Track by default:

### 1. World Track

5th Semester

- Internship / study abroad

6th Semester

- Intelligent Mobile Systems Project / Thesis Module
- Program-specific Specialization Module  
Exemplary course offering:
  - Dynamical Systems and Control
  - Advanced Control
  - Marine Robotics
  - Wireless Localization
  - Applied Nonlinear Control
  - Advanced Robotics
  - Model Order Reduction
  - Embedded Systems Design Lab

## 2. Campus Track

Students who do not enter the World Track follow the Campus Track.  
5th and 6th Semester

- Program-specific Project / Thesis Module
- Program-specific Specialization Module  
(please see World Track for exemplary course offering)
- Additional CORE Module

## 2.5 The Bachelor Thesis / Project

This module is a mandatory graduation requirement for all undergraduate students. It consists of two components in the major study program guided by a Jacobs Faculty member:

1. **A Research Project** (5 ECTS)  
and
2. **The Bachelor Thesis** (10 ECTS)

The workload for the project component is about 125 hours and for the thesis component about 250 hours. The title of the thesis will be shown on the transcript.

### 2.5.1 Aims

Within this module, students apply knowledge they have acquired about their major discipline, skills, and methods to become acquainted with actual research topics, ranging from the identification of suitable (short-term) research projects, preparatory literature searches, the realization of discipline-specific research, and the documentation, discussion, and interpretation of the results. Research results obtained from the Research Project can be embedded in the Bachelor Thesis.

## 2.5.2 Intended Learning Outcomes

### 1. Research Project

This module component consists of a guided research project in the major study program. The well-defined research task must be completed and documented according to the scientific standards in the respective discipline. It involves a high degree of independence, supported by individualized instructor feedback and guidance.

### 2. Bachelor Thesis

With their Bachelor Thesis students should demonstrate mastery of the contents and methods of the major specific research field. Furthermore, students should show the ability to analyze and solve a well-defined problem with scientific approaches, a critical reflection of the status quo in scientific literature, and an original development of their own ideas.

Both, the Research Project and the Bachelor Thesis, can also have an inter- or transdisciplinary nature - with the explicit permission of the supervisor.

## 2.5.3 Supervision

Both module components can be performed with the same Jacobs faculty member, or different ones, the latter in order to allow a broader research experience. Students are required to choose a supervisor, at the latest, by the end of the drop-add period of the semester in which the module component is taken. **The selected supervisor(s) must approve the Project topic and Bachelor Thesis topic before the student starts to work towards the module component.** The respective study program coordinators will assist in the search for prospective supervisor(s).

## 2.5.4 Registration

**World Track students** register for both components, at the earliest, in their 6th semester. **Campus Track students** register for the Project component in the 5th and for the Bachelor Thesis component, at the earliest, in their 6th semester.

The registrations must be made before the end of the respective drop/add periods.

Later enrolment is possible for those students pursuing a second major or those who graduate late for other reasons. These students perform their (second) thesis earliest in the 7th semester of their studies. They have to contact the Student Records Office for individual registration.

Students are allowed to extend their thesis related work into the intersession or summer break upon approval of the thesis supervisor and Student Records. Students are not allowed to register for different Bachelor Thesis courses in the same semester.

## 2.5.5 Formal Regulations for the Bachelor Thesis

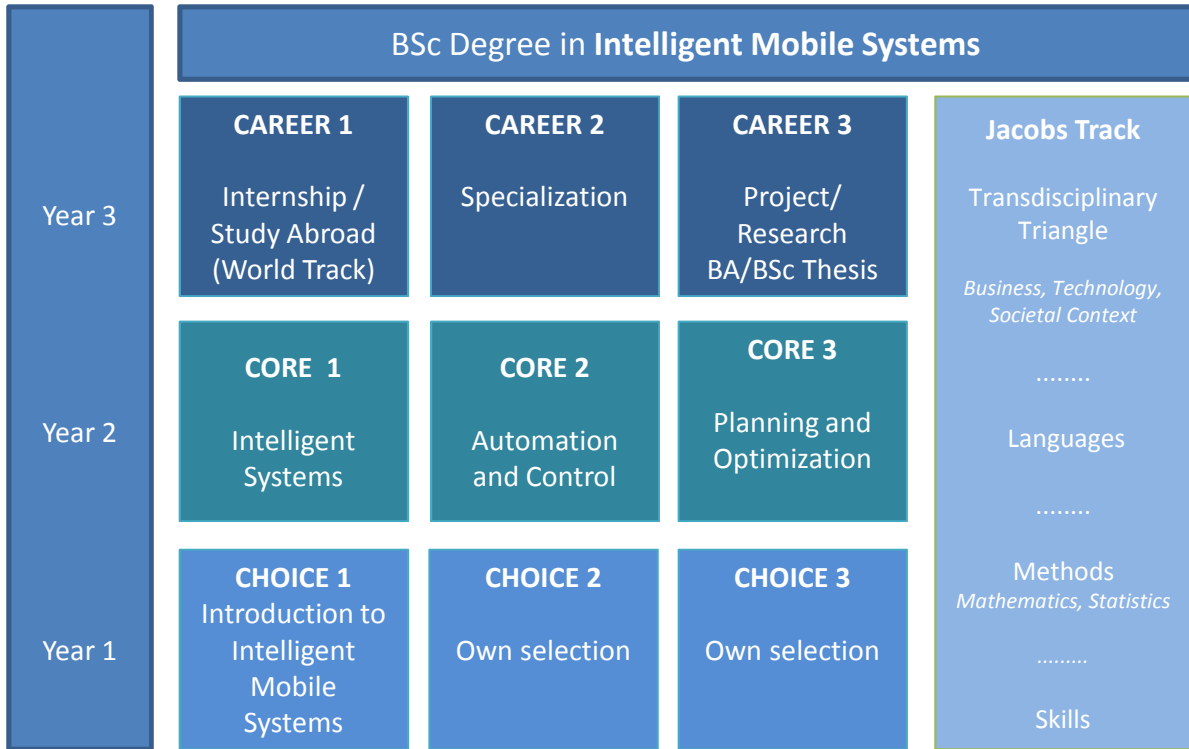
- Timing

The Thesis work has to be generated within the semester of registration. The semester period has 14 weeks.

- **Extent**  
The document must be between 15-25 pages in length, including references, but excluding appendices or supporting information. Deviations in length and format can be determined within individual study programs and should be communicated to all registered students by the study program coordinator.
- **Cover page**  
The cover page must show the title of the Bachelor Thesis, the university's name, the month and year of submission, the name of the student and the name of the supervisor.
- **Statutory Declaration**  
Each Bachelor Thesis must include a statutory declaration signed by the student confirming it is their own independent work and that it has not been submitted elsewhere. The respective form can be found on the Student Records Office website.
- **Submission**  
The Bachelor Thesis must be submitted as a hard copy (pdf-file) to the supervisor and additionally to the Student Records Office via online form on the Student Records Office website.

**Deadline for submission of the Bachelor Thesis is May 15 (unless specified otherwise by the Student Records Office).**

**2.5.6 Structure**



**YEAR 1**                      *Take three CHOICE modules, two free selection*  
**YEAR 2**                      *Take three CORE modules, one CORE module can be substituted by a CORE module from a second study program to pursue a minor*  
**YEAR 3**                      *Alternatively Campus Track with a 4th CORE module instead of internship/study abroad module*

Figure 4: Intelligent Mobile Systems Module Structure



### **3 Appendix 1a/1b: Mandatory Module and Examination Plans for World Track and Campus Track**

Jacobs University Bremen reserves the right to substitute courses by replacements and/or reduce the number of mandatory/mandatory elective courses offered.

### **4 Appendix 2: Course Data for Program-Specific CHOICE and CORE Courses**

All course data stated in the appendix is based on the previous study year and subject to change.

## Appendix 1a - Mandatory Module and Examination Plan for World Track

Intelligent Mobile Systems – World Track											
Matriculation Fall 2016											
Program-Specific Modules					Jacobs Track Modules (General Education)						
Type	Status <sup>1</sup>	Semester	Credits		Type	Status <sup>1</sup>	Semester	Credits			
<b>Year 1 - CHOICE</b>				<b>45</b>							<b>20</b>
<i>Take the mandatory CHOICE module listed below, this is a requirement for the IMS program.</i>											
<b>CH09-IntroIMS</b>	<b>Module: Introduction to Intelligent Mobile Systems</b>		<b>m</b>							<b>15</b>	
CH09-320103	General Intelligent Mobile Systems I	Lecture	m	1	5	<b>JT-ME-MethodsMath</b>	<b>Module: Methods / Mathematics</b>	<b>m</b>		<b>7,5</b>	
CH09-320113	Introduction to Intelligent Mobile Systems Lab I	Lab	m	1	2,5	JT-ME-120103	Calculus I	Lecture	m	1	2,5
CH09-320104	General Intelligent Mobile Systems II	Lecture	m	2	5	JT-ME-120104	Calculus II	Lecture	m	1	2,5
CH09-320114	Introduction to Intelligent Mobile Systems Lab II	Lab	m	2	2,5	JT-ME-120122	Foundations of Linear Algebra I	Lecture	m	2	2,5
<b>Module: CHOICE (own selection)</b>				<b>e</b>	<b>1/2</b>	<b>30</b>	<b>JT-SK-Skills</b>	<b>Module: Skills</b>	<b>m</b>		<b>5</b>
<i>Students take two further CHOICE modules from those offered for all other study programs. <sup>2</sup></i>											
<b>Year 2 - CORE</b>				<b>45</b>							<b>20</b>
<i>Take all three modules <u>or</u> replace one with a CORE module from a different study program. <sup>2</sup></i>											
<b>CO22-IntelSys</b>	<b>Module: Intelligent Systems</b>		<b>me</b>		<b>15</b>	<b>JT-ME-MethodsMath</b>	<b>Module: Methods / Mathematics</b>	<b>m</b>		<b>7,5</b>	
CO22-320671	Computer Vision	Lecture	m	3	5	JT-ME-120201	Elements of Probability	Lecture	m	3	2,5
CO22-320311	Robotics	Lecture	m	4	5	JT-ME-120113	Foundations of Linear Algebra II	Lecture	m	4	2,5
CO22-320372	Machine Learning	Lecture	m	4	5	JT-ME-120202	Numerical Methods I	Lecture	m	4	2,5
<b>CO23-AutoControl</b>	<b>Module: Automation and Control</b>		<b>me</b>		<b>15</b>	<b>JT-TA-TriArea</b>	<b>Module: Triangle Area</b>	<b>m</b>		<b>7,5</b>	
CO23-320301	Control Systems	Lecture	m	3	5	Take three courses from the triangle (BUSINESS, TECHNOLOGY & INNOVATION, SOCIETAL CONTEXT) area. Each counts 2,5 ECTS <sup>3</sup>					
CO26-300312	Embedded Systems Lab	Lab	m	3	5	<b>JT-LA-Language</b>	<b>Module: Language</b>	<b>m</b>		<b>5</b>	
CO23-320203	Automation	Lecture	m	4	5	Take two German courses (2,5 ECTS each). Native German speakers take courses in another offered language					
<b>CO24-PlanOpt</b>	<b>Module: Planning and Optimization</b>		<b>me</b>		<b>15</b>						
CO29-080202	Operations Research	Lecture	m	3	5						
CO24-300491	Optimization	Lecture	m	4	5						
CO24-320331	Artificial Intelligence	Lecture	m	3	5						
<b>Year 3 - CAREER</b>				<b>45</b>							<b>5</b>
<b>CA02 / CA03</b>	<b>Module: Internship / Study Abroad</b>		<b>m</b>	<b>5</b>	<b>20</b>	<b>JT-TA-TriArea</b>	<b>Module: Triangle Area</b>	<b>m</b>		<b>5</b>	
<b>CA01-CarSkills</b>	<b>Module: Career Skills</b>		<b>m</b>			Take two courses from the triangle (BUSINESS, TECHNOLOGY & INNOVATION, SOCIETAL CONTEXT) area. Each counts 2,5 ECTS <sup>3</sup>					
<b>CA09-IMS</b>	<b>Module: Project/Thesis IMS</b>		<b>m</b>		<b>15</b>						
CA09-320303	Project IMS		m	6	5						
CA09-320304	Thesis IMS		m	6	10						
<b>CAS-WT-IMS</b>	<b>Module: Specialization Area IMS</b>		<b>m</b>		<b>10</b>						
Take four specialization courses (2.5 ECTS each) <sup>2</sup>				<b>me</b>	<b>5/6</b>	<b>10</b>					
<b>Total ECTS</b>										<b>180</b>	

<sup>1</sup> Status (m = mandatory, e = elective, me = mandatory elective)

<sup>2</sup> For a full listing of all CHOICE / CORE / CAREER / Jacobs Track modules please consult the **CampusNet online catalogue** and / or the module handbook (on our website).

<sup>3</sup> You are required to take six Triangle Area courses in total. Select two from each of the three triangle areas (BUSINESS, TECHNOLOGY & INNOVATION, SOCIETAL CONTEXT).

## Appendix 1b - Mandatory Course Plan for Module and Examination Track

Intelligent Mobile Systems – Campus Track											
Matriculation Fall 2016											
Program-Specific Modules					Jacobs Track Modules (General Education)						
Type	Status <sup>1</sup>	Semester	Credits		Type	Status <sup>1</sup>	Semester	Credits			
<b>Year 1 - CHOICE</b>				<b>45</b>							<b>20</b>
<i>Take the mandatory CHOICE module listed below, this is a requirement for the IMS program.</i>											
<b>CH09-IntroIMS</b>	<b>Module: Introduction to Intelligent Mobile Systems</b>			<b>m</b>				<b>15</b>			
CH09-320103	General Intelligent Mobile Systems I	Lecture	m	1	5	<b>JT-ME-MethodsMath</b>	<b>Module: Methods / Mathematics</b>			<b>m</b>	<b>7,5</b>
CH09-320113	Introduction to Intelligent Mobile Systems Lab I	Lab	m	1	2,5	JT-ME-120103	Calculus I	Lecture	m	1	2,5
CH09-320104	General Intelligent Mobile Systems II	Lecture	m	2	5	JT-ME-120104	Calculus II	Lecture	m	1	2,5
CH09-320114	Introduction to Intelligent Mobile Systems Lab II	Lab	m	2	2,5	JT-ME-120122	Foundations of Linear Algebra I	Lecture	m	2	2,5
<b>Module: CHOICE (own selection)</b>				<b>e</b>				<b>1/2</b>		<b>30</b>	
<i>Students take two further CHOICE modules from those offered for all other study programs. <sup>2</sup></i>											
<b>Year 2 - CORE</b>				<b>45</b>							<b>20</b>
<i>Take all three modules <u>or</u> replace one with a CORE module from a different study program. <sup>2</sup></i>											
<b>CO22-IntelSys</b>	<b>Module: Intelligent Systems</b>			<b>me</b>				<b>15</b>			
CO22-320671	Computer Vision	Lecture	m	3	5	<b>JT-ME-MethodsMath</b>	<b>Module: Methods / Mathematics</b>			<b>m</b>	<b>7,5</b>
CO22-320311	Robotics	Lecture	m	4	5	JT-ME-120201	Elements of Probability	Lecture	m	3	2,5
CO22-320372	Machine Learning	Lecture	m	4	5	JT-ME-120113	Foundations of Linear Algebra II	Lecture	m	4	2,5
<b>CO23-AutoControl</b>	<b>Module: Automation and Control</b>			<b>me</b>				<b>15</b>			
CO23-320301	Control Systems	Lecture	m	3	5	JT-ME-120202	Numerical Methods I	Lecture	m	4	2,5
CO26-300312	Embedded Systems Lab	Lab	m	3	5	<b>JT-TA-TriArea</b>	<b>Module: Triangle Area</b>			<b>m</b>	<b>7,5</b>
CO23-320203	Automation	Lecture	m	4	5	Take three courses from the triangle (BUSINESS, TECHNOLOGY & INNOVATION, SOCIETAL CONTEXT) area. Each counts 2,5 ECTS <sup>3</sup>					
<b>CO24-PlanOpt</b>	<b>Module: Planning and Optimization</b>			<b>me</b>				<b>15</b>			
CO29-080202	Operations Research	Lecture	m	3	5	<b>JT-LA-Language</b>	<b>Module: Language</b>			<b>m</b>	<b>5</b>
CO24-300491	Optimization	Lecture	m	4	5	Take two German courses (2,5 ECTS each). Native German speakers take courses in another offered language					
CO24-320331	Artificial Intelligence	Lecture	m	3	5						
<b>Year 3 - CAREER</b>				<b>45</b>							<b>5</b>
<b>COXX</b>	<b>Module: Additional (4th) CORE module</b>			<b>m</b>				<b>5/6</b>		<b>15</b>	
<b>CA01-CarSkills</b>	<b>Module: Career Skills</b>			<b>m</b>							
<b>CA09-IMS</b>	<b>Module: Project/Thesis IMS</b>			<b>m</b>							
CA09-320303	Project IMS		m	5	5	<b>JT-TA-TriArea</b>	<b>Module: Triangle Area</b>			<b>m</b>	<b>5</b>
CA09-320304	Thesis IMS		m	6	10	Take two courses from the triangle (BUSINESS, TECHNOLOGY & INNOVATION, SOCIETAL CONTEXT) area. Each counts 2,5 ECTS <sup>3</sup>					
<b>CAS-CT-IMS</b>	<b>Module: Specialization Area IMS</b>			<b>m</b>							
Take six specialization courses (2.5 ECTS each) <sup>2</sup>				<b>me</b>				<b>5/6</b>		<b>15</b>	
<b>Total ECTS</b>										<b>180</b>	

<sup>1</sup> Status (m = mandatory, e = elective, me = mandatory elective)

<sup>2</sup> For a full listing of all CHOICE / CORE / CAREER / Jacobs Track modules please consult the **CampusNet online catalogue** and / or the module handbook (on our website).

<sup>3</sup> You are required to take six Triangle Area courses in total. Select two from each of the three triangle areas (BUSINESS, TECHNOLOGY & INNOVATION, SOCIETAL CONTEXT).

## Appendix 2 - Course Data

<b>Course Name</b> General Intelligent Mobile Systems I	<b>Course No</b> CH09-320103	<b>ECTS</b> 5
<b>Module Affiliation</b> CH09-IntroIMS Introduction to Intelligent Mobile Systems	<b>Workload (hrs / sem)</b> 125	<b>Level</b> Bachelor 1st Year CHOICE
<b>Course Description / Content / Aims</b> This course teaches the essentials of spatial geometry, kinematics, and modeling in the context of intelligent mobile systems. The course starts with a review of 3D vectors and their products, and then covers 3D rotation representations, including the Direction Cosines Matrix (DCM), Euler angle sequences, axis-angle, quaternions, and the exponential mapping. Subsequently, general 3D transforms are studied with applications to the specification and visualization of robot geometry. In parallel, students also learn to use Matlab for symbolic algebra and programming. The last part of the course deals with particle and rigid body kinematics using the general screw-theory formulation. In kinematics, there is an emphasis on examples relevant to automobiles and to other common mobile platforms.		
<b>Methods of Assessment</b>		
Name	Weighting	
Active Participation	5%	
Final Exam	20%	
Home Work, Quizzes, Programming projects	60%	
Midterm Exam	15%	
<hr/>		
<b>Course Name</b> Introduction to Intelligent Mobile Systems Lab I	<b>Course No</b> CH09-320113	<b>ECTS</b> 2,5
<b>Module Affiliation</b> CH09-IntroIMS Introduction to Intelligent Mobile Systems	<b>Workload (hrs / sem)</b> 62,5	<b>Level</b> Bachelor 1st Year CHOICE
<b>Course Description / Content / Aims</b> This lab accompanies the lecture course "General Intelligent Mobile Systems 1." Employing a high-level systems approach, the lab teaches the student how to interface a microcontroller to commonly used sensors and actuators. A comprehensive introduction to programming the popular open-source Arduino board is given in the lab. It is recommended that this lab is taken after a lab on programming in C.		
<b>Methods of Assessment</b>		
Name	Weighting	
Final Project	20%	
Task-wise demos and oral quizzes	80%	
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## Appendix 2 - Course Data

<b>Course Name</b> General Intelligent Mobile Systems II	<b>Course No</b> CH09-320104	<b>ECTS</b> 5
<b>Module Affiliation</b> CH09-IntroIMS Introduction to Intelligent Mobile Systems	<b>Workload (hrs / sem)</b> 125	<b>Level</b> Bachelor 1st Year CHOICE
<b>Course Description / Content / Aims</b> <p>The course offers an introduction to modeling, and design of linear control systems in terms of ordinary differential equations (ODEs). Students learn how to analyze and solve systems of ODEs using state and frequency space methods. Concepts covered include time and frequency response, stability, steady-state errors, and the root-locus method. The first part of the course culminates with the detailed design of the famous PID controller.</p> <p>The second part of this course teaches the derivation of ODEs describing the dynamics of typical mobile systems. To make these typically nonlinear equations amenable to linear control methods, techniques of linearization and the limits of their applicability are covered as well.</p>		
<b>Course Name</b> Introduction to Intelligent Mobile Systems Lab II	<b>Course No</b> CH09-320114	<b>ECTS</b> 2,5
<b>Module Affiliation</b> CH09-IntroIMS Introduction to Intelligent Mobile Systems	<b>Workload (hrs / sem)</b> 62,5	<b>Level</b> Bachelor 1st Year CHOICE
<b>Course Description / Content / Aims</b> <p>This laboratory course offers intense practical experience in the analysis and the design of linear control systems. Students learn how to use Matlab and Simulink tools to investigate the system behavior and to study its time and frequency response. They learn how to design feedback controls, and to interpret and take care of steady-state errors. The lab is a strongly interactive course. Students need to prepare for the sessions and evaluate their results in written reports.</p>		

## Appendix 2 - Course Data

<b>Course Name</b> Computer Vision	<b>Course No</b> CO22-320671	<b>ECTS</b> 5						
<b>Module Affiliation</b> CO22-IntelSys Intelligent Systems	<b>Workload (hrs / sem)</b> 125	<b>Level</b> Bachelor 2nd Year CORE						
<p><b>Course Description / Content / Aims</b></p> <p>Computer Vision algorithms are used in a variety of real-world applications, such as surveillance and object tracking, 3D model building (photogrammetry), and object recognition. Apart from their visual appeal, these algorithms also represent elegant applications of linear algebra and optimization techniques. Topics covered in this course include a recapitulation of relevant linear algebra, introduction to face-recognition, camera calibration, stitched panoramas, edge and blob visual features, structure from motion, color-spaces, segmentation, basic 3D point-cloud processing, and an introduction to object-recognition. It is assumed that the student can program in C++ (recommended) or Python.</p>								
<p><b>Methods of Assessment</b></p> <table style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="width: 80%;">Name</th> <th style="width: 20%;">Weighting</th> </tr> </thead> <tbody> <tr> <td>Final Exam</td> <td style="text-align: right;">20%</td> </tr> <tr> <td>Homeworks/Class exercises/Projects</td> <td style="text-align: right;">80%</td> </tr> </tbody> </table>			Name	Weighting	Final Exam	20%	Homeworks/Class exercises/Projects	80%
Name	Weighting							
Final Exam	20%							
Homeworks/Class exercises/Projects	80%							
<b>Course Name</b> Robotics	<b>Course No</b> CO22-320311	<b>ECTS</b> 5						
<b>Module Affiliation</b> CO22-IntelSys Intelligent Systems	<b>Workload (hrs / sem)</b> 125	<b>Level</b> Bachelor 2nd Year CORE						
<p><b>Course Description / Content / Aims</b></p> <p>The course gives an introduction to robotics with a particular focus on (intelligent) mobile robots. The lecture covers the according core methods and technologies to enable autonomous or semi-autonomous operations of mobile platforms. Examples of related topics include</p> <ul style="list-style-type: none"> <li>• actuators and their components, i.e., electrical motors, gears, feedback sensors</li> <li>• locomotion, especially different drive units, their physical implementation and their kinematics</li> <li>• robot control architectures</li> <li>• localization sensors and methods</li> <li>• range sensing and processing</li> <li>• map representations</li> <li>• core principles of Simultaneous Localization and Mapping (SLAM)</li> <li>• sensor data registration</li> <li>• place recognition</li> <li>• obstacle avoidance and introduction to path-planning</li> </ul>								

## Appendix 2 - Course Data



<b>Course Name</b> Machine Learning	<b>Course No</b> CO22-320372	<b>ECTS</b> 5								
<b>Module Affiliation</b> CO22-IntelSys Intelligent Systems	<b>Workload (hrs / sem)</b> 125	<b>Level</b> Bachelor 2nd Year CORE								
<p><b>Course Description / Content / Aims</b></p> <p>Machine learning (ML) is about algorithms which are fed with (large quantities of) real-world data, and which return a compressed "model" of the data. An example is the "world model" of a robot: the input data are sensor data streams, from which the robot learns a model of its environment -- needed, for instance, for navigation. Another example is a spoken language model: the input data are speech recordings, from which ML methods build a model of spoken English -- useful, for instance, in automated speech recognition systems. There exist many formalisms in which such models can be cast, and an equally large diversity of learning algorithms. However, there is a relatively small number of fundamental challenges which are common to all of these formalisms and algorithms. The lecture introduces such fundamental concepts and illustrates them with a choice of elementary model formalisms (linear classifiers and regressors, radial basis function networks, clustering, neural networks, hidden Markov models). Furthermore, the lecture also provides a refresher of required mathematical material from probability theory and linear algebra.</p>										
<b>Course Name</b> Control Systems	<b>Course No</b> CO23-320301	<b>ECTS</b> 5								
<b>Module Affiliation</b> CO23-AutoControl Automation and Control	<b>Workload (hrs / sem)</b> 125	<b>Level</b> Bachelor 2nd Year CORE								
<p><b>Course Description / Content / Aims</b></p> <p>This course is an introduction to dynamical systems and control with a focus on a broad range of applications. Topics include: 1. Low dimensional linear and non-linear autonomous dynamical systems: formulation as differential equation, flow, fixed points, stability, stability criteria, potentials, Lyapunov functions, and the Lyapunov matrix equation, simple local bifurcations (saddle-node, pitchfork, transcritical, cusp, Hopf), simple numerical schemes, time-discrete maps their fixed points and stability, introduction to chaos. 2. Control for linear systems: general matrix-based solution for driven linear ODEs, reachability, controllability, observability, constructability, Gram-matrix for determining control laws and for reconstruction, a linear-state feedback controller, stable-state estimation, and an introduction to optimal control. As a famous example for possible consequences resulting from interactions of controlled systems, we study the Turing instability in a reaction-diffusion type partial differential equation.</p>										
<p><b>Methods of Assessment</b></p> <table style="width: 100%; border-collapse: collapse;"> <thead> <tr> <th style="text-align: left;">Name</th> <th style="text-align: right;">Weighting</th> </tr> </thead> <tbody> <tr> <td>Final Exam</td> <td style="text-align: right;">30%</td> </tr> <tr> <td>Home Work</td> <td style="text-align: right;">40%</td> </tr> <tr> <td>Midterm Exam</td> <td style="text-align: right;">30%</td> </tr> </tbody> </table>			Name	Weighting	Final Exam	30%	Home Work	40%	Midterm Exam	30%
Name	Weighting									
Final Exam	30%									
Home Work	40%									
Midterm Exam	30%									

## Appendix 2 - Course Data



<b>Course Name</b> Automation	<b>Course No</b> CO23-320203	<b>ECTS</b> 5
<b>Module Affiliation</b> CO23-AutoControl Automation and Control	<b>Workload (hrs / sem)</b> 125	<b>Level</b> Bachelor 2nd Year CORE
<p><b>Course Description / Content / Aims</b></p> <p>Automation is the application of technology to monitor and control the production and delivery of products and services. The field of Automation has considerable overlap with the fields of Control and Robotics. However, the distinguishing aspect is the emphasis on industrial application, along with the concomitant focus on robustness and efficiency under factory conditions.</p> <p>Topics covered in this course include: an introduction to industrial sensors used in process control, operational principles of industrial motors and drives, an introduction to Programmable Logic Controllers (PLC), programming PLCs, fuzzy logic and controllers, and artificial intelligence (AI) concepts used in automation.</p>		
<b>Course Name</b> Embedded Systems Lab	<b>Course No</b> CO26-300312	<b>ECTS</b> 5
<b>Module Affiliation</b> CO23-AutoControl Automation and Control	<b>Workload (hrs / sem)</b> 125	<b>Level</b> Bachelor 2nd Year CORE
<p><b>Course Description / Content / Aims</b></p> <p>The goal of this lab course is to establish an understanding of the architecture of a microcontroller as well as how to program it in C and assembly language. The goal is achieved by guiding the students in an application-oriented manner through a series of design tasks like reading/controlling various sensors/actuators, processing internal/external interrupts, generation of PWM signals, and AD/DA conversion. The basic architecture of a microcontroller with its ALU, timer/counter, memory, I/O interface; the concepts of working registers, interrupt vectors, program counter will be introduced. At the end of the course, students should be able to develop and implement their own solutions for typical applications on AVR/ARM based microcontrollers.</p>		



## Appendix 2 - Course Data

<b>Course Name</b> Autonomous Systems	<b>Course No</b> CO24-320521	<b>ECTS</b> 5
<b>Module Affiliation</b> CO24-PlanOpt Planning and Optimization	<b>Workload (hrs / sem)</b> 125	<b>Level</b> Bachelor 2nd Year CORE
<b>Course Description / Content / Aims</b> There is an increasing interest and need to generate artificial systems that can carry out complex missions in unstructured environments without permanent human supervision. Intelligent mobile robots are often used as prototype or even defining example of according autonomous systems. But in a more general notion, an autonomous system can be seen as a combination of a computational core, sensors and motors, a finite store for energy, and a suited control allowing, roughly speaking, for flexible stand-alone operation that can deal with situations the designers may not have foreseen when constructing and programming the system. The investigation of autonomous systems is driven from two different perspectives. First, it is driven by the engineering aspects of generating application oriented devices like household, care-giving or security and rescue systems. Second, artificial autonomous systems offer new ways to investigate and constructively understand natural cognition.		
<b>Course Name</b> Operations Research	<b>Course No</b> CO29-080202	<b>ECTS</b> 5
<b>Module Affiliation</b> CO24-PlanOpt Planning and Optimization CO29-ProcessEng Process Engineering	<b>Workload (hrs / sem)</b> 125	<b>Level</b> Bachelor 2nd Year CORE
<b>Course Description / Content / Aims</b> Operations research is an interdisciplinary mathematical science that focuses on the effective use of technology by organizations. By employing techniques such as mathematical modeling, statistical analysis, and mathematical optimization, operations research finds optimal or near-optimal solutions to complex decision-making problems. Operations Research is concerned with determining the maximum (of profit, performance, or yield) or the minimum (of loss, risk, or cost) of some real-world objective. This course introduces students to modelling of decision problems and the use of quantitative methods and techniques for effective decision-making. Familiarity with a programming language (e.g., Python, C++, etc.) is desirable for this course.		
<b>Methods of Assessment</b>		
Name	Weighting	
Final Examination	40%	
Homework	30%	
Midterm Exam	30%	

## Appendix 2 - Course Data



<b>Course Name</b> Optimization	<b>Course No</b> CO24-300491	<b>ECTS</b> 5
<b>Module Affiliation</b> CO24-PlanOpt Planning and Optimization	<b>Workload (hrs / sem)</b> 125	<b>Level</b> Bachelor 2nd Year CORE
<b>Course Description / Content / Aims</b> Optimization is a key step in the design of systems and processes. The course starts with classical search techniques like bisection, golden section, Newton's algorithm, and conjugate gradient. It then discusses constrained problems like linear and quadratic programming based on the Lagrange formalism, and gives a first introduction to the concepts of convex optimization, in particular convex sets, convex functions, optimality conditions and duality. The course comes with a wide variety of examples and applications.		